

Chapter 12

Structure of the model code

12.1 Source code files

The main code files, located in the **source** directory, can be classified into distinct groups, using their file name.

- Files with suffix *.f90* are FORTRAN source code files, files with *.F90* are FORTRAN files containing C-language code (`#ifdef`) statements.
- Files whose name start with a lower case character and include no underscore character, contain “declaration modules” with declarations of variables and arrays as described in Section 8.1.5.
- Files whose name start with a lower case character and include an underscore character, contain module routines, as described in Section 8.1.5. The routines are often generic and of a general nature.
- Files whose name start with an upper case character (except *Usrdef_** files) are external subprograms with “actual” code.
- Files whose name start with *Usrdef_*, contain routines for user setup. (The ones in the **source** directory are empty and intended for proper compilation only, user-defined versions are defined elsewhere).

Table 12.1: List of declaration module files.

file name	contents
<i>currents.f90</i>	(2-D and 3-D) current arrays
<i>datatypes.f90</i>	definitions of all derived types, used in the program
<i>density.f90</i>	density arrays
<i>depths.f90</i>	water depth and surface elevations arrays
<i>diffusion.f90</i>	horizontal and vertical diffusion coefficient arrays
<i>fluxes.f90</i>	arrays of surface and bottom fluxes, drag and exchange coefficients, roughness lengths
<i>grid.f90</i>	model grid arrays
<i>gridpars.f90</i>	model grid and related parameters
<i>iopars.f90</i>	parameters and arrays for all kind of I/O (including user-defined)
<i>meteo.f90</i>	surface meteorological arrays
<i>modids.f90</i>	key id definitions of physical model variables
<i>nestgrids.f90</i>	parameters and arrays for sub-grid nesting applications
<i>obconds.f90</i>	arrays for 2-D and 3-D open boundary conditions, arrays for 1-D surface forcing
<i>optics.f90</i>	optical arrays (including irradiance)
<i>paralpars.f90</i>	parameters and arrays needed for parallel applications
<i>physpars.f90</i>	physical model parameters
<i>relaxation.f90</i>	arrays for applying relaxation conditions
<i>sedarrays.f90</i>	sediment model arrays
<i>sedids.f90</i>	key id definitions of sediment model variables
<i>sedpars.f90</i>	sediment model parameters
<i>sedswitches.f90</i>	sediment model switches
<i>structures.f90</i>	parameters and arrays for the structure and discharge units
<i>switches.f90</i>	physical model switches
<i>syspars.f90</i>	“system” parameter constants
<i>tide.f90</i>	parameters and arrays for tidal applications
<i>timepars.f90</i>	date and time parameters
<i>turbpars.f90</i>	turbulence model constants
<i>turbulence.f90</i>	turbulence model arrays

Table 12.2: List of module routine files.

file name	contents
<i>array_interp.f90</i>	routines for interpolation on the model grid
<i>cf90_routines.F90</i>	library of netCDF routine calls
<i>check_model.f90</i>	routines for checking of user-defined parameters and arrays in the physical model
<i>check_sediments.f90</i>	routines for checking of user-defined parameters and arrays in the sediment model
<i>cif_routines.f90</i>	utility routines used for reading and writing a CIF
<i>comms_MPI.F90</i>	library of MPI routine calls
<i>datatypes_init.f90</i>	initialisation of derived type scalar and array variables
<i>default_model.f90</i>	default settings for the physical model
<i>default_sediments.f90</i>	default settings for the sediment model
<i>diagnostic_routines.F90</i>	utility routines calculating terms in the energy equation, total energy, potential energy, enstrophy and vorticity
<i>error_routines.F90</i>	routines performing error checking
<i>fft_library.f90</i>	routines for performing fast Fourier transforms
<i>grid_interp.f90</i>	routines for performing interpolation from and to external grids and locations
<i>grid_routines.f90</i>	utility routines performed on the model grid
<i>inout_parallel.f90</i>	routines for preparing input/output in parallel mode
<i>inout_routines.f90</i>	routines for performing input/output in standard format
<i>math_library.f90</i>	library of diverse mathematical routines (e.g. root finder)
<i>model_output.f90</i>	routines for defining standard output data in the physical model
<i>modvars_routines.f90</i>	attributes of variables and files in the physical model
<i>nla_library.F90</i>	linear algebra library
<i>parallel_comms.f90</i>	parallel communication library
<i>parallel_utilities.f90</i>	utility routines for parallel applications
<i>reset_model.F90</i>	reset setup parameters and arrays in the physical model defined by the user
<i>reset_sediments.f90</i>	reset setup parameters and arrays in the sediment model defined by the user
<i>rng_library.f90</i>	random generator library
<i>sediment_output.f90</i>	routines for defining standard output data in the sediment model
<i>sedvars_routines.f90</i>	attributes of variables and files in the sediment model
<i>time_routines.f90</i>	(calendar) date and time utility routines
<i>turbulence_routines.F90</i>	routines used by the turbulence subprogram
<i>utility_routines.f90</i>	various utility routines

Table 12.3: List of files with external procedures.

file name	contents
<i>Advection_Terms.F90</i>	advective terms in the transport equations
<i>Allocate_Sediment_Arrays.f90</i>	allocate/deallocate variables with a global scope for the sediment model
<i>Allocate_Sediment_Arrays.f90</i>	allocate/deallocate variables with a global scope for the sediment model
<i>Bottom_Fluxes.f90</i>	bottom drag coefficient and shear stress
<i>Coherens.Program.f90</i>	COHERENS main program
<i>Corrector_Terms.F90</i>	corrector terms in the transport equations
<i>Density_Equations.F90</i>	salinity and temperature equations, optical module, equation of state, baroclinic pressure gradient
<i>Diffusion_Coefficients.F90</i>	horizontal and vertical diffusion coefficients
<i>Diffusion_Terms.F90</i>	diffusion terms in the transport equations
<i>Grid_Arrays.F90</i>	model grid parameters and arrays (grid spacings, pointer arrays, open boundary locations, water depths)
<i>Harmonic_Analysis.f90</i>	harmonic analysis
<i>Hydrodynamic_Equations.F90</i>	hydrodynamic equations (currents, 2-D mode, elevations)
<i>Model_Finalisation.f90</i>	finalise physical model
<i>Model_Initialisation.F90</i>	initialise physical model
<i>Model_Parameters.f90</i>	read/write a CIF for the physical model
<i>Nested_Grids.F90</i>	sub-grid nesting
<i>Open_Boundary_Conditions.f90</i>	apply open boundary conditions
<i>Open_Boundary_Data_2D.f90</i>	define 2-D open boundary conditions and update data
<i>Open_Boundary_Data_Prof.f90</i>	define 3-D open boundary conditions and update data
<i>Parallel_Initialisation.f90</i>	initialise parallel mode (parameters, domain decomposition, ...)
<i>Relaxation_Zones.f90</i>	define and apply relaxation conditions
<i>Sediment_Bottom_Fluxes.F90</i>	near bed boundary conditions, (skin) shear stress and roughness length, and critical shear stress in the sediment model
<i>Sediment_Density_Equations.F90</i>	sediment contributions in the calculations within the physical model involving density
<i>Sediment_Equations.F90</i>	COHERENS sediment module (main part)

(Continued)

Table 12.3: *Continued*

<i>Sediment_Finalisation.f90</i>	finalise sediment model
<i>Sediment_Initialisation.F90</i>	initialise sediment model
<i>Sediment_Parameters.f90</i>	read/write a CIF for the sediment model
<i>Structures_Model.f90</i>	structure (dry cells, thin dams, weirs, barriers) and discharge model units
<i>Surface_Boundary_Data_1D.f90</i>	define and apply surface forcing conditions (slope and elevation) for the water column mode
<i>Surface_Data.f90</i>	update 2-D external forcing data
<i>Surface_Fluxes.F90</i>	surface fluxes
<i>Surface_Grids.f90</i>	define 2-D external grids
<i>Tidal_Forcing.F90</i>	astronomical argument, nodal factors, tidal force
<i>Time_Averages.f90</i>	time-averaged output
<i>Time_Series.f90</i>	time series output
<i>Transport_Equations.F90</i>	solve transport equations
<i>Turbulence_Equations.F90</i>	turbulence models

Table 12.4: List of user-defined routine files.

file name	contents
<i>Usrdef_Harmonic_Analysis.f90</i>	parameters and data for harmonic analysis and output
<i>Usrdef_Model.f90</i>	“basic” model setup (model parameters, bathymetry, domain decomposition, initial conditions, open boundary conditions)
<i>Usrdef_Nested_Grids.f90</i>	setup of sub-grids for nesting
<i>Usrdef_Output.f90</i>	output completely specified by the user
<i>Usrdef_Sediment.f90</i>	setup of the sediment model
<i>Usrdef_Surface_Data.f90</i>	definition of external 2-D grids and update of 2-D external data
<i>Usrdef_Time_Averages.f90</i>	parameters and data for time-averaged output
<i>Usrdef_Time_Series.f90</i>	parameters and arrays for time series output

12.2 Structure diagrams

12.2.1 General structure

The general structure of the program is given in Figure 12.1. The program

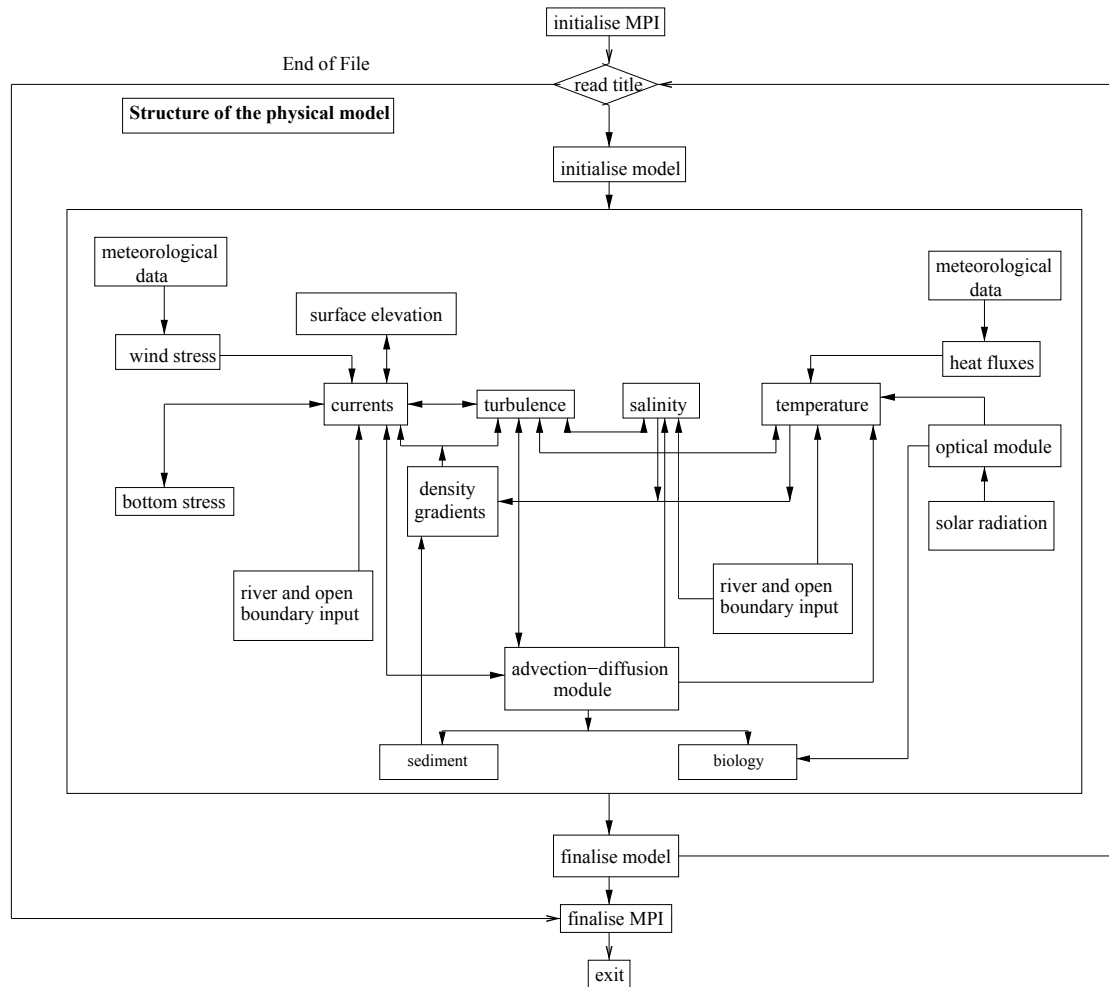


Figure 12.1: General structure of COHERENS.

contains two major loops.

- The first (outer) loop is contained within the large (semi-)rectangle. Each cycle corresponds to a new simulation, initiated by reading a next input line from the file *defruns*. This is further discussed in Section 14.1.
- The second (inner) loop within the smaller rectangle denotes the time-stepping.

Each simulation is composed of three parts: initialisation, time-stepping (where the actual calculations are performed) and finalisation. Details are given below. Initialisation and finalisation of MPI are the only procedures outside the outer loop. This means that, although multiple simulations can be performed within one run, they must all be conducted either in serial or in parallel mode.

The advection-diffusion module forms the central “core” part of the time-loop section. The module is coded in a generic way and solves the advective-diffusive transport equations of any scalar variable (temperature, salinity, sediment concentrations, biological state variables, ...), 3-D and 2-D currents, and turbulence transport equations. The inputs for the routine are prepared in separate routines for each variable (temperature, salinity, 3-D currents, 2-D currents, sediments, turbulent energy, ...) and are composed of source terms, open boundary and surface forcing data. The boundary data are obtained via general routine calls. For example, there is one program module (discussed in Section 12.2.4 below) dealing with reading and updating of open boundary profile data for any 3-D quantity.

12.2.2 Initialisation procedures

The initialisation procedures are schematically presented in Figure 12.2. Except for user output, all initialisation routines are called from `initialise_model`.

The first task to be performed by the program is the definition of all parameters and arrays needed to setup the application. This is organised in different sections.

1. Model parameters:

- model switches
- date and time parameters (start and end date, time steps)
- model grid (dimensions, resolution, number of open sea and river boundaries)
- various parameters like number and type of tidal constituents, number of nested sub-grids, ...
- parameters for setting up the model in parallel mode
- physical model parameters
- numerical model parameters
- parameters for the turbulence sub-module(s)
- attributes of external 2-D grids

- attributes of the forcing files
- parameters to define the type and form of monitoring
- parameters and switches for the sediment transport module

For details see Chapter 14.

2. Model grid and bathymetry:

- coordinates of the model grid
- bathymetry
- location of open boundaries

For details see Sections 15.1.

3. Domain decomposition (parallel mode, see Section 14.9). Once the model grid and domain decomposition have been defined, memory is allocated to all model grid arrays and a series of additional arrays (grid spacings, pointer arrays, ...) are defined.
4. Initial conditions (see Section 15.2 for the physics and 19.2 for the sediments).
5. Definition of the areas for application of the open boundary relaxation scheme (Section 16.3).
6. Locations of nested sub-grid(s) (see Section 17.3).
7. Positions of external 2-D data grids (Section 17.2).
8. Type and form of open boundary conditions for the 2-D mode (Section 16.1.1), baroclinic currents and all 3-D scalars (Section 16.2.1).
9. Initialise surface and bottom fluxes.
10. Parameters for setting up user defined output (see Chapter 20).

Open boundary and surface forcing data are usually given as time series. If the first data time coincides with the initial time, the data file is opened and the first and (eventually second) time records are read from the file during the initialisation phase of the program. This has the further advantage that error checking can be performed (existence of the file, data formats, ...) before the program enters the time loop.

Model parameters and switches for the different model compartments (physics, sediments) can be defined either in a `usrdef_` routine or by reading from a Central Input File (CIF).

Each section of the initialisation contains (or may contain) the following sub-tasks:

1. Defaults values are given to several model parameters and arrays. In many cases, these defaults are meaningful and should be maintained. In other case, they are not meaningful and must be replaced by the user. The advantage of such procedure is a more efficient error checking.
2. Values are (re)-defined. Two methods are available:
 - The definitions are programmed by the user in a `usrdef_` routine. Options are foreseen in the program to write these definitions to an external file in COHERENS standard format.
 - All values are obtained as input from an external file in COHERENS standard format.
3. Depending on the definitions given by the user, parameters are reset from their default values.
4. The setup of the model (definitions of model parameters and arrays) are checked for errors. If errors are detected, appropriate messages are written to an *errlog* file and the program aborts.

12.2.3 Time loop

Figure 12.3 shows a diagram of the time loop. The order of routine calls is in line with the solution procedure described in Section 5.8.

The routines where the 2-D mode, 3-D current, temperature, salinity and sediment transport equations are solved, are schematically presented in Figures 12.4–12.8. Each routine is composed of an initialisation section, a main part where the variable(s) is (are) updated and a finalisation section.

initialisation Actions performed during the initialisation phase (time $t=0$): allocation of local arrays, definition of open boundary conditions, opening of data files and reading of first time records.

- The initialisation of the 2-D mode is actually performed in routines `update_2dcbc_data` called from `current_2d` and `define_2dcbc_spec` called from `update_2dcbc_data`.
- Open boundary conditions for 3-D currents are defined in `current_cor`.

- If the temperature equation is forced with SST, the SST grid and data are defined and initialised in `temperature_equation`.

main section

- update open boundary data
- apply open boundary conditions
- apply surface and bottom boundary conditions (3-D variables only)
- calculate source terms
- solve the transport equations by calling the appropriate transport routine
- exchange array sections with neighbouring sub-domains (parallel mode only)
- write interpolated data for nested sub-grids (if requested)

finalisation Deallocate arrays at the current or final time step.

The following remarks are to be given:

- Surface elevations are updated in `current_2d` before the depth-integrated transports.
- Open boundary conditions are applied in `current_2d` after solving the 2-D depth-integrated momentum equations.
- The 3-D current calculations are split over two routines called at different (predictor and corrector) time steps: surface and bottom boundary conditions are applied, source terms calculated and transport equations solved in `current_pred`; open boundary conditions and corrector step are applied, vertical currents calculated and nested output written in `current_corr`.
- Besides routines for solving the transport equations for all sediment fractions, the sediment model provides separate routines for update of the bed or total load transport.
- Meteorological forcing data are defined by a separate call to `meteo_input` from the main program.

The update of a 2-D or 3-D quantity by an advection-diffusion type equation is performed in one of the `transport_at_*` routines, which integrates the model equations in time. Exceptions are surface elevation and vertical current which are obtained from the 2-D and 3-D continuity equations. The procedures closely follow the numerical descriptions given in Chapter 5 so that no diagrams need to be given here.

12.2.4 Open boundary and surface forcing data input

The procedure for applying open boundary conditions for the 2-D mode is summarised in Figure 12.9:

1. The routine `update_2dobc_data` is called from `current_2d`:
 - At the initial time the routine `define_2d_obc_spec` is called where
 - A series of arrays to be specified by the user, are allocated.
 - The arrays are defined by calling either the user-defined routine `usrdef_2dobc_spec` or as input from a standard COHERENS file by calling `read_2dobc_spec`. If requested, the arrays are written to a standard file by calling `write_2dobc_spec`.
 - Error checking is performed.
 - If there are external data files, it is checked first for each data file, whether the data are still up to date, which means that the last date and time for which data are available is later than the current one. If this is not the case (such as at the initial time), `define_2d_obc_data` is called where:
 - New data are obtained by calling either the user-defined routine `usrdef_2dobc_data` or as input from a standard COHERENS file by calling `read_2dobc_data`. If requested, the arrays are written to a standard file by calling `write_2dobc_data`.
 - If an end of file condition occurs, further action is determined by the `endfile` attribute. This is further discussed in Section 14.7.2.
 - The new data (if any), representing the ψ_0^e term in equation (4.354), are stored in the appropriate open boundary arrays and interpolated in time (if requested).
 - Harmonic tidal expansions are evaluated. If needed (which is usually the case at the initial time), astronomical arguments and nodal factors are calculated by calling `astro_params`. The harmonic terms are added to the data values.
2. The open boundary conditions are applied by calling `open_boundary_conds_2d`.

User-defined setup for 2-D open boundary conditions is further discussed in Section 16.1.

The procedure for applying open boundary conditions for the 3-D mode is given in Figure 12.10. The code is written in a generic form so that the routines can be used for any 3-D quantity (currents, temperature, ...).

1. At the initial time the routine `define_profobc_spec` is called from the “main” routine (`current_corr`, `temperature_equation`, ...):
 - A series of arrays to be specified by the user, are allocated.
 - The arrays are defined by calling either the user-defined routine `usrdef_profobc_spec` or as input from a standard COHERENS file by calling `read_profobc_spec`. If requested, the arrays are written to a standard file by calling `write_profobc_spec`.
 - Error checking is performed.
2. The routine `update_profobc_data` is called where:
 - It is checked first for each data file, whether the data are still up to date, which means that the last date and time for which data are available is later than the current one. If this is not the case (such as at the initial time), `define_profobc_data` is called where:
 - New data are obtained by calling either the user-defined routine `usrdef_profobc_data` or as input from a standard COHERENS file by calling `read_profobc_data`. If requested, the arrays are written to a standard file by calling `write_profobc_data`.
 - If an end of file condition occurs, further action is determined by the `endfile` attribute. This is further discussed in Section 14.7.2.
 - The new data (if any) are stored in the appropriate open boundary profile arrays and interpolated in time (if requested).
 - If any of the interpolating values has a flagged value, the interpolated open boundary profile data value will be flagged as well. A flagged value at a certain vertical level within a vertical profile means that a zero gradient condition will be applied at that particular level.
3. The open boundary conditions are applied by calling `open_boundary_conds_3d` for baroclinic currents or `open_boundary_conds_prof` for scalars.

User-defined setup for baroclinic open boundary conditions is further discussed in Section 16.2.

The application of 2-D external data requires firstly the definition of the data grid, which is implemented as follows (no diagram shown):

1. A derived type “grid” array is created by allocation in the “main” routine (`meteo_input` for the meteo, `temperature_equation` for the SST

grid or `wave_input` for surface waves), for storing the relative coordinates of the data grid with respect to the model grid (see Section 8.1.4).

2. The grid is defined by calling `define_surface_input_grid`. Definition depends on the value `nhtype` grid attribute (see Section 10.4.2):
 - 0: No grid needs to be defined
 - 1: The grid is uniform rectangular and is defined by calling `construct_regular_grid`.
 - 2: The grid is non-uniform rectangular. Coordinate arrays are obtained by calling either the user-defined routine `usrdef_surface_absgrd` or as input from a standard COHERENS file by calling `read_surface_absgrd`. If requested, the coordinates are written to a standard file by calling `write_surface_absgrd`. The relative coordinates are obtained by calling `model_to_data_coords`.
 - 3: The grid is non-uniform and non-rectangular. The relative coordinate arrays are directly obtained by calling either the user-defined routine `usrdef_surface_relgrd` or as input from a standard COHERENS file by calling `read_surface_relgrd`. If requested, the coordinates are written to a standard file by calling `write_surface_relgrd`.
 - 4: The grid coincides with the model grid and does not need to be defined here.

Setup of 2-D data grids is discussed in Sections 17.2.1–17.2.2.

The procedure for the input of forcing data from a 2-D external data grid is shown in Figure 12.11. The code is written in a generic form so that the routines can be used for meteorological, SST, wave, ... data. The routine `update_surface_data` is called from the “main” routine (`meteo_input` for the meteo or `temperature_equation` for the SST grid):

1. It is checked first for each data file, whether the data are still up to date, which means that the last date and time for which data are available is later than the current one. If this is not the case (such as at the initial time), `define_surface_data` is called where:
 - New data are obtained by calling either the user-defined routine `usrdef_surface_data` or as input from a standard COHERENS file by calling `read_surface_data`. If requested, the arrays are written to a standard file by calling `write_surface_data`.
 - If an end of file condition occurs, further action is determined by the `endfile` attribute. This is further discussed in Section 14.7.2.

2. The data are interpolated in time.
3. If any of the interpolating values has a flagged value, the interpolated open boundary profile data value will be flagged as well. In case of SST data, the flagged value is replaced by the modelled temperature at the highest level. There is currently no procedure foreseen for flagged meteorological data values.
4. The data are interpolated in space by calling `intpol_data_to_model_2d` if $0 < \text{nhtype} < 4$.

12.2.5 Finalisation procedures

After termination of the time loop the simulation is finalised as follows:

- All files, which are still open with exception of monitoring files, are closed.
- A timer report is written on request.
- Model arrays, which are still allocated, are deallocated.
- All monitoring files are closed.
- A new input line is read from the *defruns* file. If there is an end of file condition, the program checks whether MPI was switched on at the start, finalises MPI if needed and terminates. Otherwise, a new simulation starts and all model parameters and arrays are reset to their default values as part of the re-initialisation procedures discussed in Section 12.2.2.

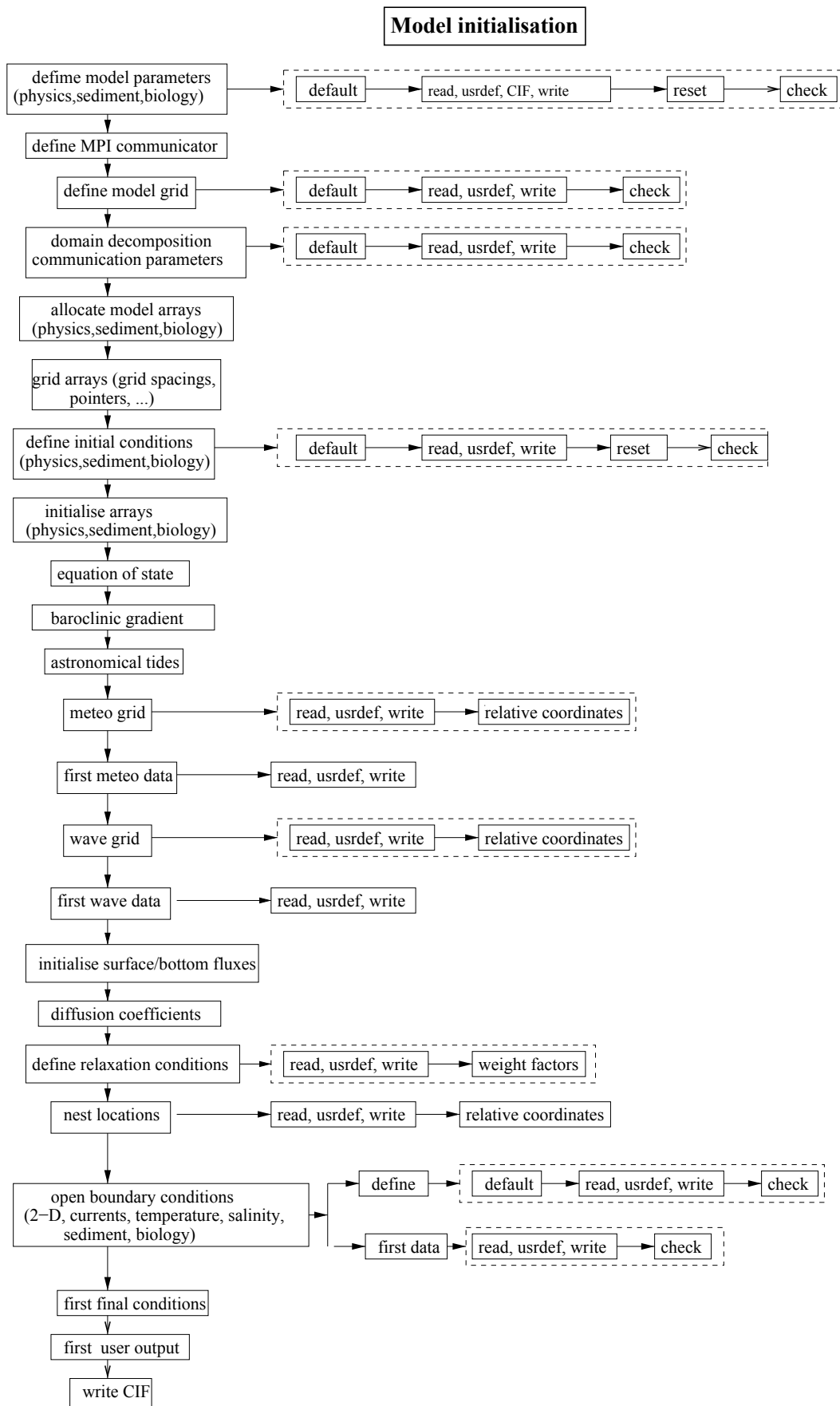


Figure 12.2: Schematic diagram of all initialisation procedures.

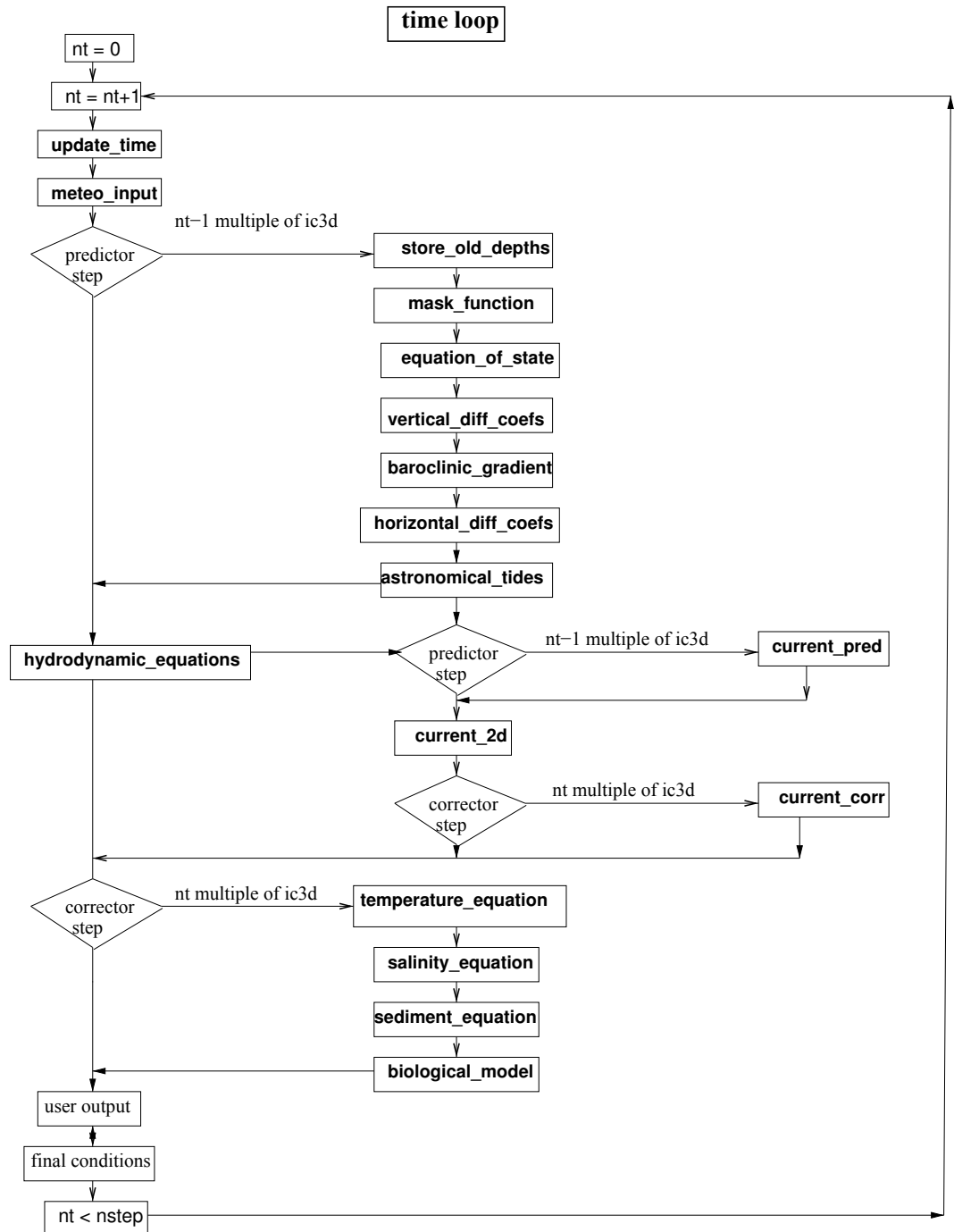


Figure 12.3: Structure diagram of the time loop.

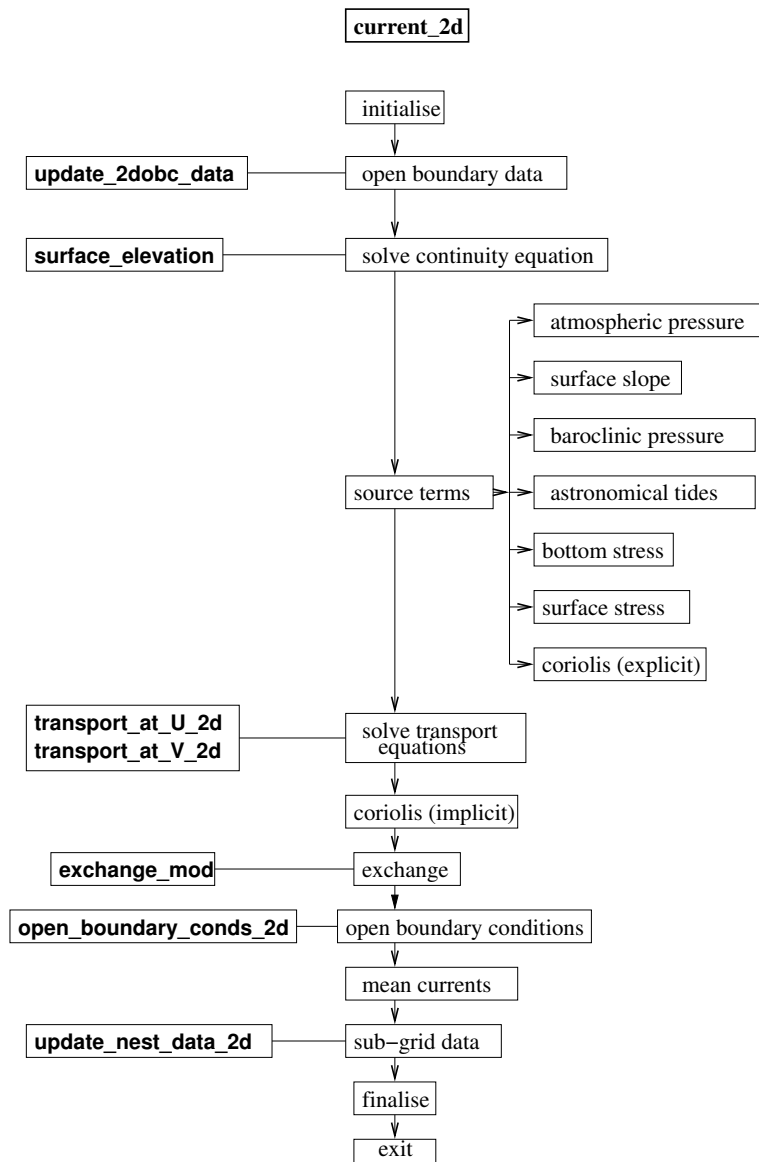


Figure 12.4: Diagram of routine `current_2d` which solves the 2-D mode equations.

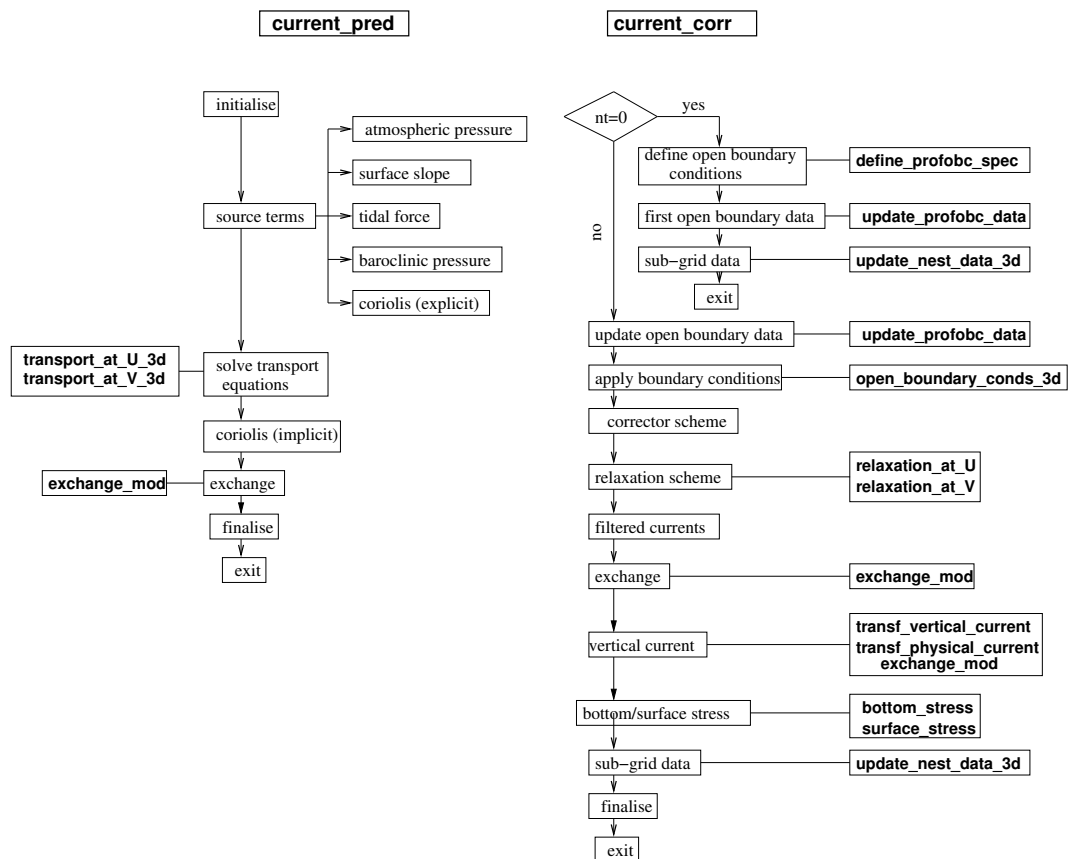


Figure 12.5: Diagrams of the routines `current_pred` and `current_corr` which solve the 3-D momentum equation at the predictor and corrector step.

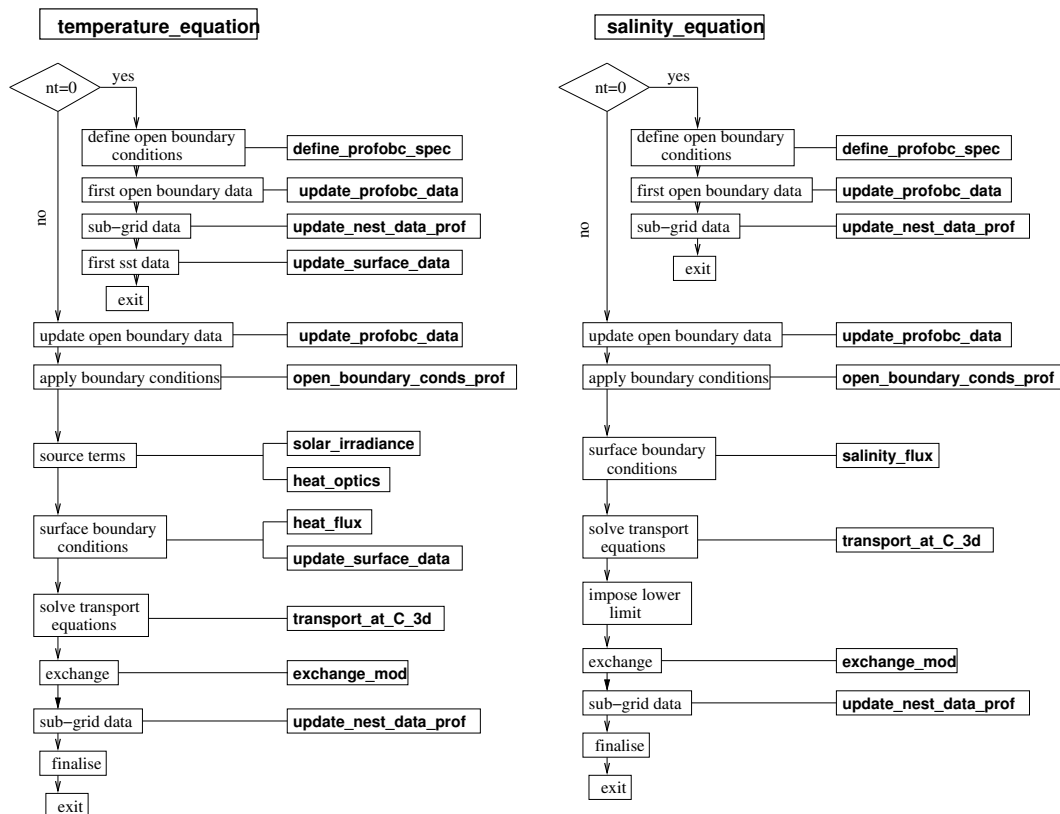


Figure 12.6: Diagrams of the routines `temperature_equation` and `salinity_equation` which solve the temperature and salinity equations.

Sediment equations

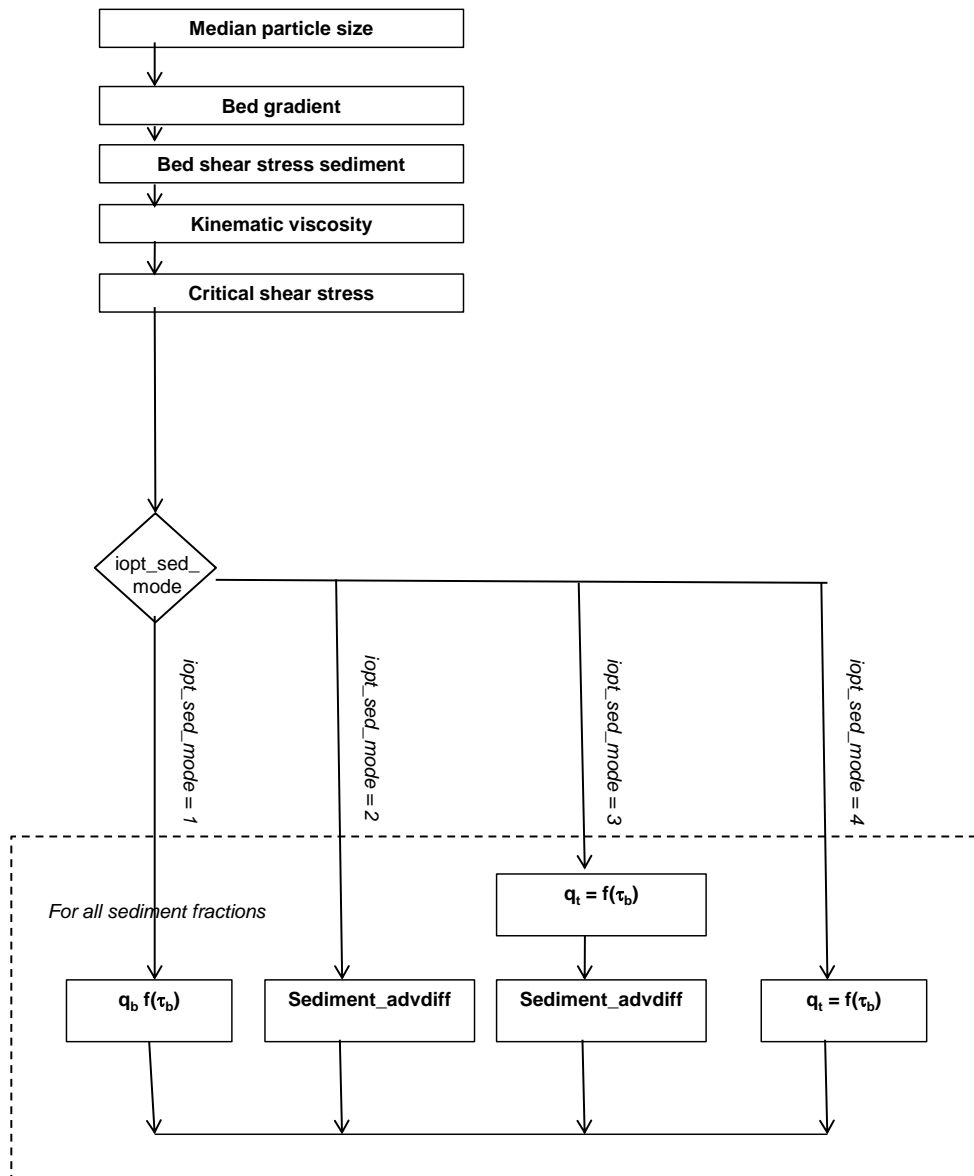


Figure 12.7: Diagram of the routine `sediment_equation` which is the “main” routine of the sediment transport model.

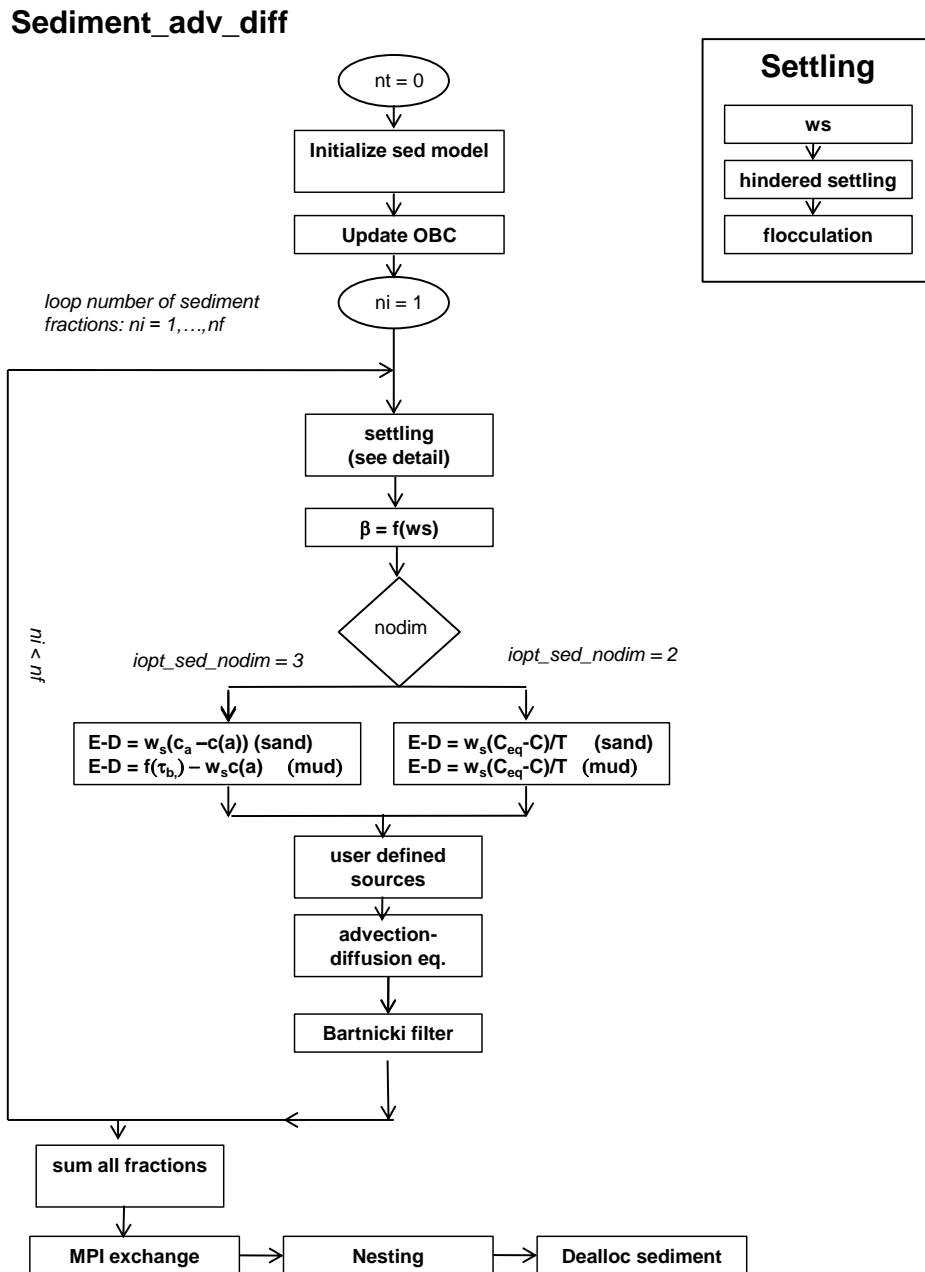


Figure 12.8: Diagram of the routine `sediment_advdiff_equation` which solves the transport equations for sediments.

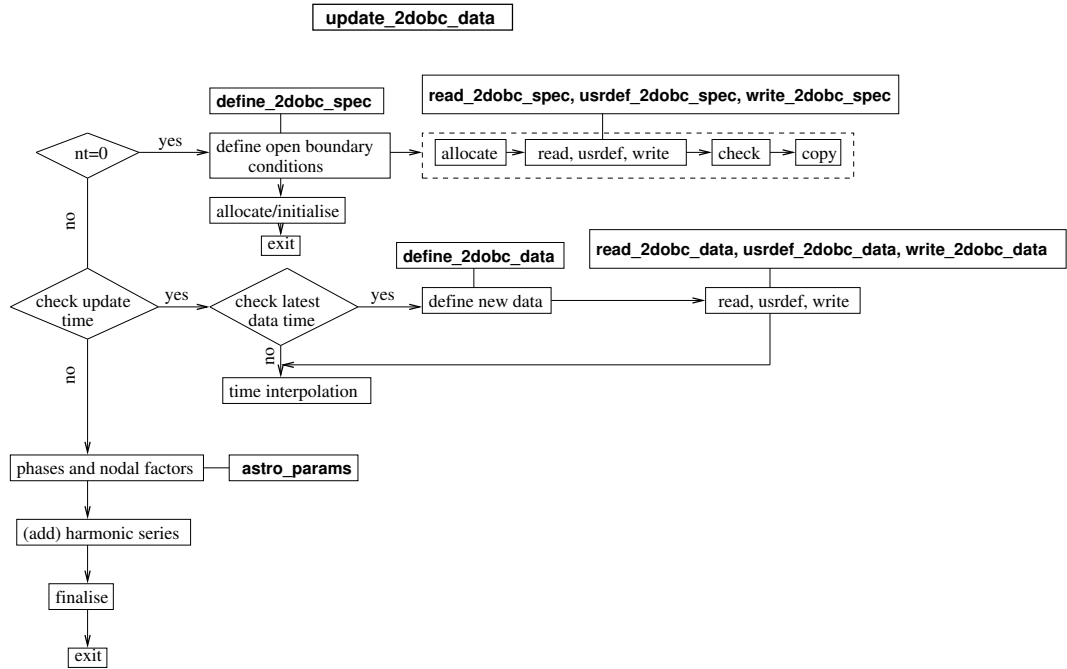


Figure 12.9: Diagrams of the routines used for defining and updating 2-D open boundary conditions and data.

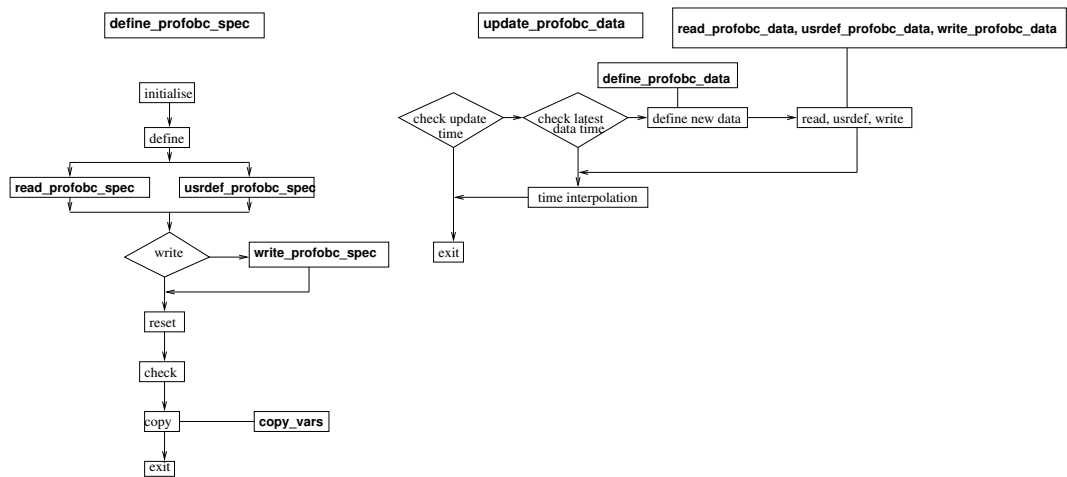


Figure 12.10: Diagrams of the routines used for defining and updating 3-D open boundary conditions and data.

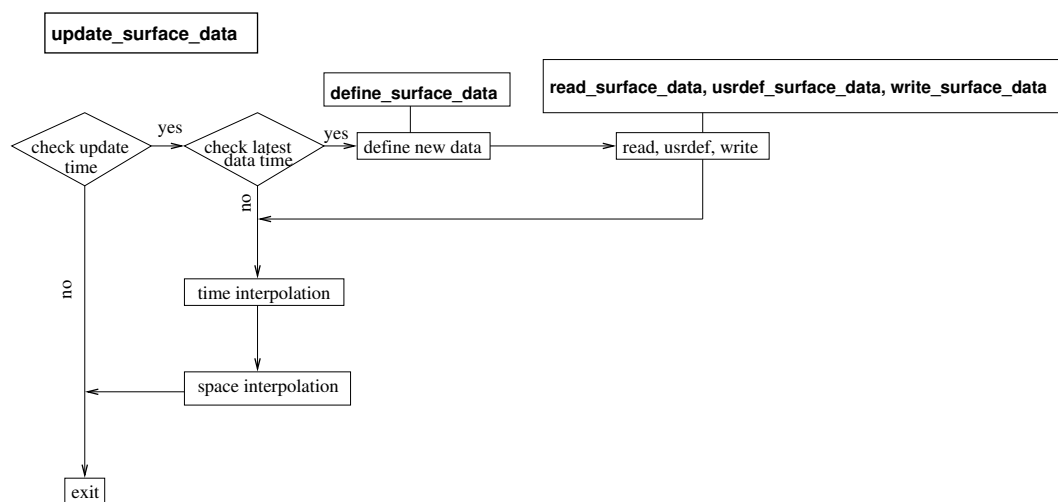


Figure 12.11: Diagram of the routines used for defining and updating data from an external 2-D grid.

