Appendix D

Energy balance equation

The energy balance equation is derived by multiplying equations (4.61), (4.62), (4.60) by respectively $\rho_0 u$, $\rho_0 v$, $\rho_0 g \zeta$ and adding. For simplicity the baroclinic and atmospheric pressure gradients, the tidal force and horizontal diffusion are neglected. After a straightforward calculation one obtains

$$\frac{1}{h_3}\frac{\partial}{\partial t}(h_3E_k) + \frac{1}{H}\frac{\partial E_p}{\partial t} + \frac{1}{h_1h_2h_3} \left[\frac{\partial}{\partial \xi_1}(h_2h_3F_1) + \frac{\partial}{\partial \xi_2}(h_1h_3F_2) \right] = D \quad (D.1)$$

where

$$E_k = \frac{1}{2}\rho_0(u^2 + v^2) \tag{D.2}$$

is the kinetic energy,

$$E_p = \frac{1}{2}\rho_0 g \zeta^2 \tag{D.3}$$

the potential energy,

$$(F_1, F_2) = \left(\frac{1}{2}\rho_0(u^2 + v^2) + \rho_0 g\zeta\right)(u, v, \omega)$$
 (D.4)

the energy flux vector and

$$D = \rho_0 \left(\frac{u}{h_3} \frac{\partial D_1}{\partial s} + \frac{v}{h_3} \frac{\partial D_2}{\partial s} \right)$$
 (D.5)

the dissipation of energy by turbulent diffusion. The diffusion fluxes are given by

$$(D_1, D_2) = \left(\frac{\nu_T}{h_3} \frac{\partial u}{\partial s}, \frac{\nu_T}{h_3} \frac{\partial v}{\partial s}\right) \text{ inside the water column}$$

$$= (\tau_{s1}, \tau_{s2}) \text{ at the surface}$$

$$= (\tau_{b1}, \tau_{b2}) \text{ at the bottom}$$
(D.6)

The vertically integrated form of (D.1) becomes

$$\frac{\partial}{\partial t}(\overline{E}_k + E_p) + \frac{1}{h_1 h_2} \left[\frac{\partial}{\partial \xi_1} (h_2 \overline{F}_1) + \frac{\partial}{\partial \xi_2} (h_1 \overline{F}_2) \right] = \overline{D}$$
 (D.7)

where

$$\overline{E}_k = \frac{1}{2}\rho_0 \int_0^{N_z} h_3(u^2 + v^2) ds$$
 (D.8)

$$(\overline{F_1}, \overline{F_2}) = \int_0^{N_z} h_3 \left[\frac{1}{2} \rho_0(u^2 + v^2) + \rho_0 g \zeta \right] (u, v) ds$$
 (D.9)

$$\overline{D} = \rho_0 \left(u_s \tau_{s1} + v_s \tau_{s2} - u_b \tau_{b1} - v_b \tau_{b2} \right) - \rho_0 \int_0^{N_z} \frac{\nu_T}{h_3} \left[\left(\frac{\partial u}{\partial s} \right)^2 + \left(\frac{\partial v}{\partial s} \right)^2 \right] ds \quad (D.10)$$

where (u_s, v_s) and (u_b, v_b) are the velocities at respectively the surface and the bottom.

In case of a pure 2-D application, $u \simeq \overline{u}$ and $v \simeq \overline{v}$ in which case (D.7)–(D.10) reduce to

$$\overline{E}_k = \frac{1}{2}\rho_0 H(\overline{u}^2 + \overline{v}^2) \tag{D.11}$$

$$(\overline{F_1}, \overline{F_2}) = H\left[\frac{1}{2}\rho_0(\overline{u}^2 + \overline{v}^2) + \rho_0 g\zeta\right](\overline{u}, \overline{v})$$
 (D.12)

$$\overline{D} = \rho_0 (u_s \tau_{s1} + v_s \tau_{s2} - u_b \tau_{b1} - v_b \tau_{b2})$$
(D.13)

Finally, the domain integrated forms are obtained by integrating (D.7) over the 2-D horizontal domain. This gives

$$\frac{\partial}{\partial t} \left(\langle \overline{E}_k \rangle + \langle E_p \rangle \right) + \int (\overline{F}_1 n_1 + \overline{F}_2 n_2) \, d\ell = \langle \overline{D} \rangle \tag{D.14}$$

with

$$\langle \cdots \rangle = \int_0^{N_x} \int_0^{N_y} (\cdots) h_1 h_2 \, d\xi_1 d\xi_2 \tag{D.15}$$

The second integral is taken along the 2-D boundary of the domain where (n_1, n_2) is the outwards pointing unit normal along the boundary.